

A complete parametrization of galaxy bias

Fabian Schmidt
MPA

Mirbabayi, FS, Zaldarriaga (MSZ), arXiv:1412.5169

Clarification: what do I mean by bias ?

- I mean a *perturbative bias expansion*:

$$\delta_g(\mathbf{x}, \tau) = \sum_O b_O(\tau) O(\mathbf{x}, \tau)$$

- Goal is to identify which operators O and corresponding bias parameters b_O we need to keep
 - at each order in perturbation theory (PT)
 - be agnostic: should apply to *any tracer*
- Why ? PT is the only approach that allows us a *rigorous error control* on our theory prediction - for any tracer

Bias: open questions

- Historically, “local bias” ansatz:

$$O \in \{\delta, \delta^2, \dots\}$$

Fry & Gaztanaga

- Recently, has become clear that we need to include biasing with respect to *tidal field*

$$O \in \{(K_{ij})^2, (K_{ij})^3, \delta(K_{ij})^2, \dots\}$$

$$K_{ij} = \left(\partial_i \partial_j - \frac{1}{3} \delta_{ij} \nabla^2 \right) \Phi$$

- Often referred to as “nonlocal bias”

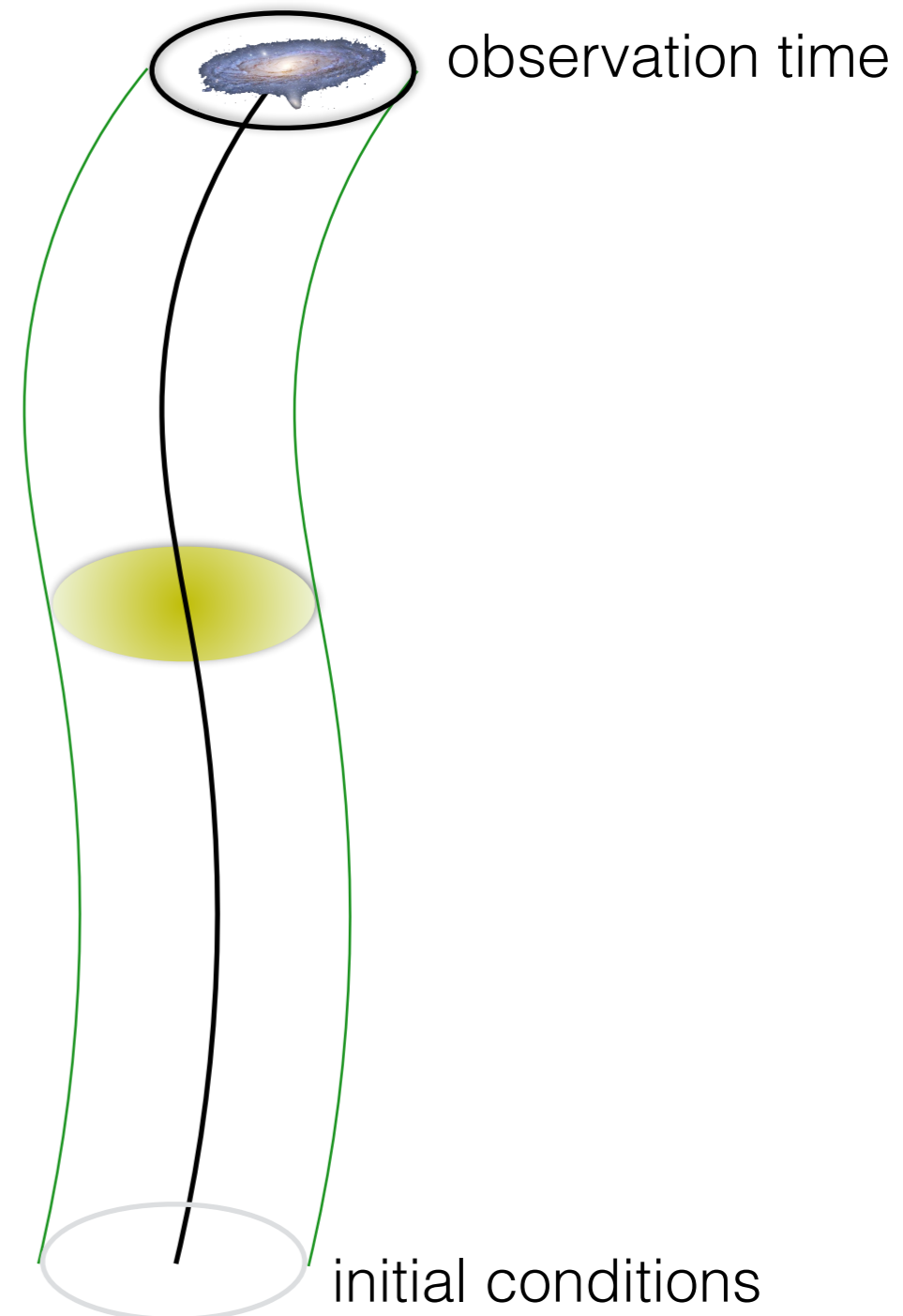
McDonald & Roy
Chan et al, Baldauf et al

Bias: open questions

- We can thus use set of operators $O \in \{\delta, \delta^2, (K_{ij})^2, \dots\}$
- *But this leaves several questions:*
 - How do we know it is complete (describes any tracer ?)
 - Lagrangian vs Eulerian biasing (evaluate O 's at initial or final time ?)
 - What about scale-dependent bias ?
 - And velocity bias ?

A general framework for bias

- Local galaxy density n_g can only depend on local observables, determined by *equivalence principle*:
 - density δ and tidal field K_{ij} *
- However, in general n_g will depend on these observables *along the entire past trajectory* (geodesic)
- Equivalently, galaxy density depends on time derivatives of local observables



* also, spatial derivatives -> later; assume Gaussian adiab. IC here

General bias expansion

- That is, set of operators should include δ , K_{ij} as well as $D^n/Dt^n \{\delta^2, K_{ij}, \dots\}$, where *D/Dt is convective (or Lagrangian) time derivative*
- Want to work out which terms to keep at given order in PT: i.e., need a *complete non-redundant set* (without double-counting) of operators
- MSZ give Eulerian and Lagrangian examples
- Key trick: use that in PT,

$$\delta = D(t)\delta^{[1]}(\mathbf{x}) + D^2(t)\delta^{[2]}(\mathbf{x}) + \dots$$

General bias expansion

- Example: up to third order,

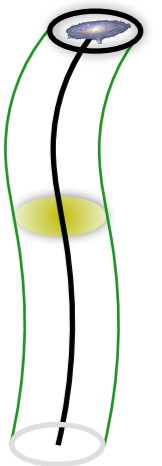
$$\begin{aligned} \delta_g(\mathbf{x}_{\text{fl}}(\tau), \tau) = & \sum_{n=1}^3 \frac{b_n^E}{n!} \delta^n + \sum_{n=2}^3 \frac{b_{K^n}^E}{n!} \text{Tr} [K_{ij}^n] + \frac{1}{6} b_{\delta K^2}^E \delta \text{Tr} [K_{ij}^2] \\ & + \frac{1}{6} b_{\text{nloc}}^E K^{ij} \frac{\partial_i \partial_j}{\nabla^2} \left(\delta^2 - \frac{3}{2} \text{Tr}[K_{ij}^2] \right) \end{aligned}$$

Nonlocal* term, induced by time evolution

(this term was introduced in different form before;
truly new operators from evolution appear at 4th
order)

Virtues of a complete bias parametrization

- *Unambiguous set of bias parameters* at each order in PT
 - E.g., want to calculate N -pt function to m loops ? This tells you exactly how many and which biases you need
- Works *equivalently in Eulerian and Lagrangian space* (or anything in between)
- Does not make any assumptions about where in time halo/galaxy formation happens

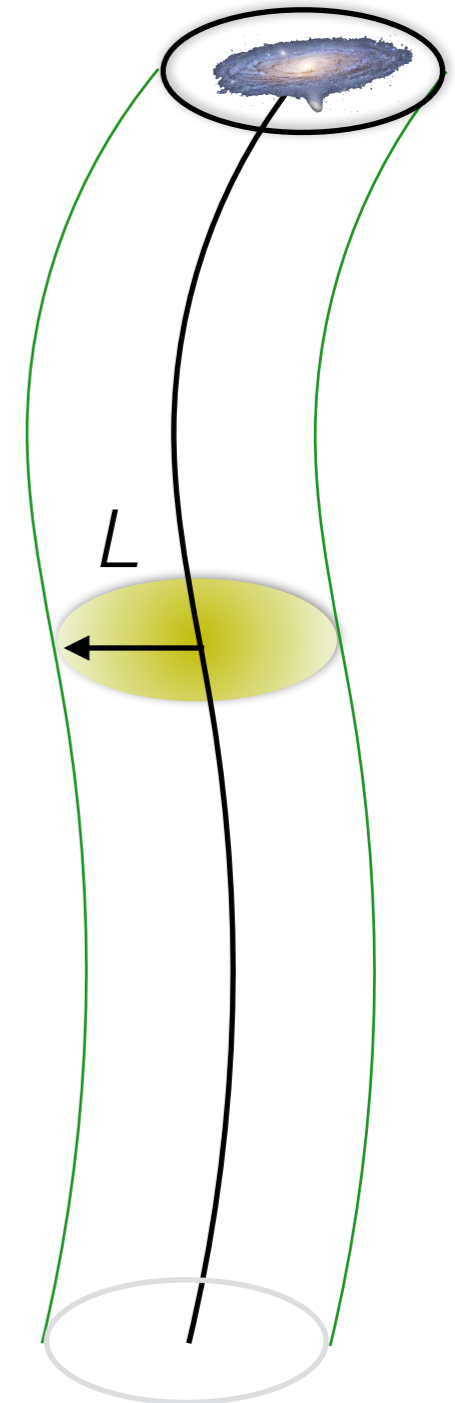


Higher derivative biases

- Treatment so far is valid if density and tidal field perturbations are *effectively spatially constant* as far as the local galaxy is concerned: *lowest order in spatial derivatives*
- However, galaxies will care about detailed matter distribution within in some finite region $\sim L$ around them
- Dependence on matter distribution (a functional) can be expanded in terms of spatial derivatives:

$$\delta_g \supset L^2 \partial^2 \delta, L^4 \partial^4 \delta, L^2 \partial_i \delta \partial^i \delta \dots$$

↙ Scale-dep. bias $\sim k^2 L^2$



Virtues of higher derivative biases

- Physically, they are there (e.g. required for consistency by renormalization)
- By marginalizing over L , and coefficients, we effectively *smoothly cut off information on small scales* which depend on details of galaxy formation, feedback, etc.
 - Fitting $P(k)$ and $\xi(r)$ then amounts to the same information - not true for sharp k_{\max} and r_{\min} !
- Given matter $P(k)$ and L , *theory tells us how many higher derivative biases we need* at desired order in PT

Remark: what is “nonlocal” bias ?

- All operators in bias expansion have to be local observables
- in this sense, *bias is always local!*
- Beyond this, it is a matter of definition: nonlocal bias is...
 - anything that is not a power of δ , e.g. $(K_{ij})^2$
(*traditional bias literature*)
 - anything that is nonlocal in $\partial_i \partial_j \Phi$, e.g. $K^{ij} \frac{\partial_i \partial_j}{\nabla^2} \left(\delta^2 - \frac{3}{2} \text{Tr}[K_{ij}^2] \right)$
(*some current literature*)
 - These latter terms are local observables because they are convective time derivatives of local observables

Remark: what is “nonlocal” bias ?

- All operators in bias expansion have to be local observables
- in this sense, *bias is always local!*
- Beyond this, it is a matter of definition: nonlocal bias is...
 - anything that is not a power of δ , e.g. $(K_{ij})^2$
(*traditional bias literature*)
 - anything that is nonlocal in $\partial_i \partial_j \Phi$, e.g. $K^{ij} \frac{\partial_i \partial_j}{\nabla^2} \left(\delta^2 - \frac{3}{2} \text{Tr}[K_{ij}^2] \right)$
(*some current literature*)
 - These latter terms are local observables because they are convective time derivatives of local observables

For completeness...

- In general, also have to allow for *stochasticity*. Each operator should come, in addition, multiplied by a stochastic field ε .

For example, up to third order,

$$\delta_g^{\text{stoch}} = \epsilon_0^* + \epsilon_\delta^E \delta + \frac{1}{2} \epsilon_{\delta^2}^E \delta^2 + \frac{1}{2} \epsilon_{K^2}^E \text{Tr} [K_{ij}^2] \quad \text{where } \varepsilon_i \text{ are completely characterized by 1-pt PDF}$$

- *Velocity bias*: at lowest order in derivatives, the equivalence principle requires that there is *no velocity bias*. Leading correction is of the form

$$\mathbf{v}_g = \mathbf{v} + L^2 \partial^2 \mathbf{v}$$

Summary (I)

- There exists a *unique bias expansion* which describes the relation between a general tracer and matter perturbations - based only on homogeneity/isotropy and the equivalence principle.
- These should allow for rigorous cosmology constraints from galaxy (and Ly α) statistics on quasilinear scales, *without making any assumptions* about galaxy formation, HOD, etc.
- There are *two cut-offs of the perturbative description*: the nonlinear scale where $\delta \sim 1$, and L , the scale over which galaxy formation happens. Which one is bigger is still unknown ! (and presumably depends on galaxy sample)

Summary (II)

- Of course, this results in a large number of bias parameters: here, *simulations and semi-analytics* can be extremely useful by constraining relations between bias parameters*
- Further topics not covered here: (please ask!)
 - rigorous embedding in GR context
 - connection to initial conditions (f_{NL} in single field...)
 - application to intrinsic alignments

*For precision measurements of b_{δ^n} , see Titouan Lazeyras' poster!