## On Model Selection in Cosmology

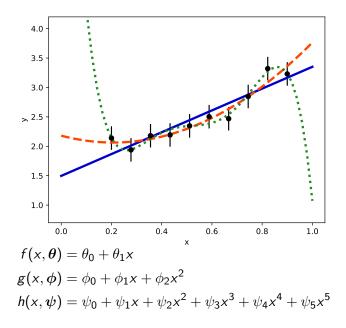
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M.Kerscher, J.Weller: https://arxiv.org/abs/1901.07726

#### Numquam ponenda est pluralitas sine necessitate.





#### Parameter estimation (briefly)

Model selection Goodness of fit Likelihood ratio test Bayesian model comparison Information theoretic approach: classical and Bayesian

The expansion history of the Universe

Discussion

#### Parameter estimation

- Measurements  $\boldsymbol{d} = (x_i, y_i)_{i=1}^N$ .
- Model  $f(x, \theta)$  with parameters  $\theta \in A \subset \mathbb{R}^{K}$ .
- Objective: determine θ\* such that f(x, θ\*) is the best approximation to the data d, such that f(x<sub>i</sub>, θ\*) is approximation y<sub>i</sub>.

All methods start with the likelihood - here a Gaussian likelihood:

$$p_f(\boldsymbol{d} \mid \boldsymbol{\theta}) = \left( (2\pi)^N \det(\boldsymbol{\Sigma}) \right)^{-\frac{1}{2}} \exp\left( -\frac{1}{2} \sum_{i=1}^N (\boldsymbol{y} - \boldsymbol{f})^T \boldsymbol{\Sigma}^{-1} (\boldsymbol{y} - \boldsymbol{f}) \right)$$

 $\boldsymbol{y} = (y_1, \dots, y_N)^T$ ,  $\boldsymbol{f} = (f(x_1, \boldsymbol{\theta}), \dots, f(x_N, \boldsymbol{\theta}))^T$ , covariance matrix  $\boldsymbol{\Sigma}$ .

## Maximum likelihood and least square

• Maximum likelihood: Find  $\theta^*$  maximising  $p_f(\boldsymbol{d} \mid \theta^*)$ .

In choosing the parameter  $\theta^*$ , the data points become the most probable data points given the model f.

• Least square: simplified maximum likelihood with Gaussian likelihood and diagonal Σ.

Searching for maximum of the log-likelihood

$$\log p_f(\boldsymbol{d} \mid \boldsymbol{\theta}) = \text{const.} - \frac{1}{2} \sum_{i=1}^{N} \frac{(y_i - f(x_i, \boldsymbol{\theta}))^2}{\sigma_i^2}$$

is equivalent to searching for the minimum of

$$\chi_f^2 = \sum_{i=1}^N \frac{(y_i - f(x_i, \boldsymbol{\theta}))^2}{\sigma_i^2}$$

#### Bayesian parameter estimation

- Prior distribution  $p_f(\theta)$  of the parameters for model  $f(x, \theta)$ .
- Posterior distribution  $p_f(\theta \mid d)$  from Bayes theorem

$$p_f(oldsymbol{ heta} \mid oldsymbol{d}) = rac{p_f(oldsymbol{d} \mid oldsymbol{ heta}) \,\, p_f(oldsymbol{ heta})}{p_f(oldsymbol{d})}$$

• Evidence (or marginal likelihood):

$$p_f(\boldsymbol{d}) = \int p_f(\boldsymbol{d} \mid \boldsymbol{\theta}) \ p_f(\boldsymbol{\theta}) \mathrm{d}\boldsymbol{\theta}.$$

• Maximum posterior estimate (MAP):  $\theta^*$  maximising  $p_f(\theta^* | \boldsymbol{d})$ .



• Consider two models

 $f(x, \theta)$  with parameters  $\theta \in A \subset \mathbb{R}^{K}$ ,  $g(x, \phi)$  with parameters  $\phi \in B \subset \mathbb{R}^{L}$ .

- Determine  $\theta^*$  and  $\phi^*$  (with your favourite method).
- Which one is better,  $f(x, \theta^*)$  or  $g(x, \phi^*)$  ?

### Goodness of fit

• With the best fit parameters  $heta^*$  calculate

$$\chi_f^2 = \sum_{i=1}^N \frac{(y_i - f(x_i, \theta^*))^2}{\sigma_i^2}$$

• Reduced– $\chi^2$ 

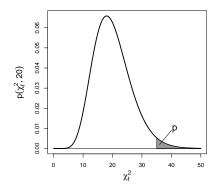
$$\chi^2_{f,\rm red} = \frac{\chi^2_f}{n_{\rm df}}$$

typically  $n_{df} = N - K$ .

 $\begin{array}{l} - \ \chi^2_{f,\mathrm{red}} \approx 1 \text{ a good fit,} \\ - \ \chi^2_{f,\mathrm{red}} > 1 \text{ a bad fit, and} \\ - \ \chi^2_{f,\mathrm{red}} < 1 \text{ an overfit.} \end{array}$ 

## Hypothesis test and p-value

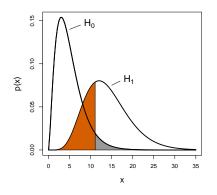
N data points independent and with Gaussian error, then  $\chi_f^2$  follows  $\chi^2$ -distribution with N-1 degrees of freedom.



- *p*-value:  $p = 1 G_{N-1}(\chi_f^2)$ indicates how incompatible the data are with our model (the null hypothesis)
- Level of significance  $\alpha$ , often  $\alpha = 0.05$ .
- If p < α our model, the null-hypothesis gets rejected.

Given the model (the null-hypothesis), a small *p*-value allows us to reject the model but we do not learn anything about the false negative rate.

## Error of the first and of the second kind



- Our model *H*<sub>0</sub> and the alternative model *H*<sub>1</sub>
- H<sub>0</sub> is **not** rejected ("accepted") at the significance level α = 0.05.
- Assume  $H_1$  is true, then the false negative rate is  $\beta = 0.32$ .

 $\begin{array}{l} \alpha \ \ \, \mbox{type I error, false positive rate (grey)} \\ \beta \ \ \, \mbox{type II error, false negative rate (red)} \end{array}$ 

### Likelihood ratio test

• Nested models: f is a special case of g (i.e.  $A \subsetneq B$  and  $f|_A \equiv g|_A$ ).

**Null hypothesis:** "*f* is the true model with  $\theta^* \in A$ " **Alternative hypothesis:** "*g* is the true model with  $\phi^* \in B$ "

• Likelihood ratio

$$L = \frac{p_f(\boldsymbol{d} \mid \boldsymbol{\theta}^*)}{p_g(\boldsymbol{d} \mid \boldsymbol{\phi}^*)}$$

- large samples:  $-2 \log L$  is  $\chi^2$ -distributed with d.f.  $\nu = \dim B - \dim A$ .

- 
$$p = 1 - G_{\nu}(-2 \log L)$$
,  
discard null-hypothesis if  $p < \alpha$   
with significance level  $\alpha$ 

 Neyman-Pearson Lemma: the test based on the likelihood ratio is minimising the false negative rate.

## Bayesian model comparison

• Probability of model f and data d:  $p(f \text{ and } d) = p_f(d) \pi_f$ similarly for model g:  $p(g \text{ and } d) = p_g(d) \pi_g$ 

 $\pi_f$  and  $\pi_g$  prior probabilities of our models.

Bayes factor

$$rac{p(f ext{ and } oldsymbol{d})}{p(g ext{ and } oldsymbol{d})} = rac{p_f(oldsymbol{d})}{p_g(oldsymbol{d})} \equiv B_{fg}$$

(assuming  $\pi_f = \pi_g$ ).

 B<sub>fg</sub> > 1 then favour model f over model g (compare Jeffreys' scale). • Evidence (marginal Likelihood)

$$p_f(\boldsymbol{d}) = \int p_f(\boldsymbol{d} \mid \boldsymbol{\theta}) \ p_f(\boldsymbol{\theta}) \mathrm{d}\boldsymbol{\theta}$$

(nested sampling, Chib's method, population MC, direct integration)

 BIC: asymptotic for large N (Schwarz 1978)

## Information theoretic approach

 Compare the predictive distribution p<sub>p,f</sub>(d) to the *true* probability p<sub>T</sub>(d) using Kulback–Leibler (KL) divergence (relative entropy)

$$D(p_T | p_{p,f}) = \int p_T(d) \log \frac{p_T(d)}{p_{p,f}(d)} dd$$
$$= \underbrace{\int p_T(d) \log p_T(d) dd}_{\text{independent of model } f} - \int p_T(d) \log p_{p,f}(d) dd$$

• Classical approach: use **predictive likelihood** (marginalised Likelihood):

$$p_{p,f}(d_i) \equiv p_f(d_i \mid \boldsymbol{\theta}) = \int p_f(\boldsymbol{d} \mid \boldsymbol{\theta}) \, \mathrm{d} \boldsymbol{d}_{[i]}$$

with  $\boldsymbol{d}_{[i]} = ((x_1, y_1), \dots, (x_{i-1}, y_{i-1}), (x_{i+1}, y_{i+1}), \dots, (x_N, y_N))^T$ .

## Classical information theoretic approach I

compare predictive likelihood p<sub>f</sub>(d | θ\*) with parameter θ\* to true distribution p<sub>T</sub>(d):

$$D(p_T | p_f) = \underbrace{\operatorname{const}}_{\text{independent from f}} - \underbrace{\int p_T(d) \log p_f(d | \theta^*) \, \mathrm{d}d}_{\eta(f)}$$

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• The expected log likelihood:

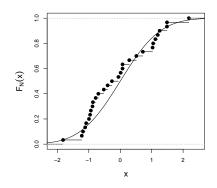
$$\eta(f) = \int \log p_f(d \mid \boldsymbol{\theta}^*) \, \mathrm{d}F_T(d),$$

• Expectation over the true distribution  $F_T$  — not available.

### Insertion: Empirical distribution function

Cumulative distribution function

$$F(x) = \int_{-\infty}^{x} p(x') \mathrm{d}x'$$



- $\{x_1, \ldots, x_N\}$  i.i.d. from F.
- Empirical distribution function

$$F_N(x) = rac{1}{N} \sum_{i=1}^N I_{[x_i,\infty)}(x)$$

• Glivenko-Cantelli:  $\|F_N - F\|_{\infty} \to 0$  uniformly

### Classical information theoretic approach II

$$D(p_T | p_f) = \operatorname{const}(f) - \underbrace{\int \log p_f(d | \theta^*) \, \mathrm{d}F_T(d)}_{\eta(f)}$$

• Estimate  $\eta(f)$  by replacing  $F_T(d)$  with  $F_{T,N}(d)$ 

$$\widehat{\eta}(f) = \int \log p_f(d \mid \boldsymbol{\theta}^*) \, \mathrm{d}F_{T,N}(d) = \frac{1}{N} \sum_{i=1}^N \log p_f(d_i \mid \boldsymbol{\theta}^*)$$

• However  $\widehat{\eta}(f)$  is biased ( $\theta^*$  is point estimate) with

$$b(f) = \int \left(\widehat{\eta}(f) - \eta(f)\right) \mathrm{d}F_{\mathcal{T}}.$$

## AIC and beyond

• b(f) asymptotically goes like K/N (Akaike, 1972)

$$\operatorname{AIC}(f) \equiv -2N\left(\widehat{\eta} - K/N\right) = -2\sum_{i=1}^{N} \log p_f(d_i \mid \boldsymbol{\theta}^*) + 2K,$$

the model with a smaller value of the AIC is favoured.

• Estimate  $\widetilde{b}(f)$  using bootstrap, then

$$\operatorname{EIC}(f) \equiv -2N\left(\widehat{\eta}(f) - \widetilde{b}(f)\right),$$

the model with a smaller value of the EIC is favoured.

#### Bayesian information theoretic approach

Compare  $p_{\text{ppd},f}(d)$  to true  $p_T(d)$  with KL-divergence

Posterior predictive distribution:

$$p_{\mathsf{ppd},f}(d) = \int p_f(d \mid \theta) \, p_f(\theta \mid d) \, \mathrm{d}\theta.$$

$$D(p_T \mid p_{\text{ppd},f}) = \text{const} - \underbrace{\int \log p_{\text{ppd},f}(d) \, \mathrm{d}F_T(d)}_{\kappa(f)}$$

• Estimate  $\kappa(f)$  using empirical distribution  $F_{T,N}$ 

$$\widehat{\kappa}(f) = \frac{1}{N} \sum_{i=1}^{N} \log \left( \underbrace{\int p_f(d_i \mid \theta) p_f(\theta \mid \boldsymbol{d}) d\theta}_{i=1} \right)$$

estimate from the MC chain

• Bayesian Predictive Information Criterium

$$\mathsf{BPIC}(f) \equiv -2N \ \widehat{\kappa}(f)$$

## The methods

- goodness of fit:  $\chi^2_{\rm red}$ , *p*-value
- likelihood ratio test: *p*-value
- Bayesian: Bayes factor and BIC
- Classical information theoretic approach: AIC, EIC
- Bayesian information theoretic approach: BPIC



- SN la's: redshift z and magnitude → distance modulus μ Union 2.1 (Suzuki et al. 2011) N = 580 data points d<sub>i</sub> = (z<sub>i</sub>, μ<sub>i</sub>)
- Distance modulus redshift relation

$$\mu(z, \theta) = 5 \log_{10} d_L(z, \theta) + 25$$

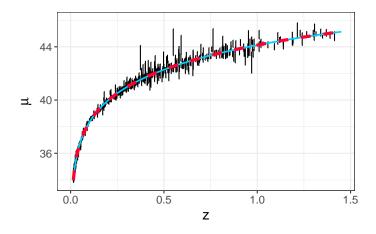
model dependence through luminosity distance  $d_L(z, \theta)$ .

• ACDM (with  $\Omega_{\Lambda} = 1 - \Omega_m$ )

$$d_L(z,\Omega_m) = d_H \left(1+z\right) \int_o^z \frac{\mathrm{d}z'}{\sqrt{\Omega_m (1+z')^3 + \Omega_\Lambda}} \; ,$$

• wCDM model (with constant e.o.s.  $p = w\varrho$ )

$$d_{L}(z,\Omega_{m},w) = d_{H}(1+z) \int_{o}^{z} \frac{dz'}{\sqrt{\Omega_{m}(1+z')^{3} + \Omega_{\Lambda}(1+z')^{3(1+w)}}}$$



• ACDM (blue):  $\Omega_m = 0.278 \pm 0.007$ 

• wCDM (red):  $\Omega_m = 0.279 \pm 0.06$  and  $w = -1.0 \pm 0.13$ 

Goodness of fit:

$$\chi^2_{
m red}(\Lambda) = 0.971, \ p_{\Lambda} = 0.68 \qquad \chi^2_{
m red}(w) = 0.973, \ p_w = 0.67$$

Likelihood ratio test:

 $p = 1 - G_1(-2\log L) = 0.975$ 

Bayesian approach:

 $BIC_{\Lambda} = -231.1$   $BIC_{w} = -224.8$ 

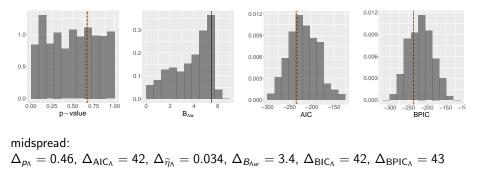
 $B_{\Lambda w} = \frac{p_{\Lambda}(d)}{p_{w}(d)} = 5.45$  substantial evidence for  $\Lambda \text{CDM}$  (Jeffreys' scale)

Classical information theoretic approach:

 $AIC_{\Lambda} = -235.5$   $AIC_{w} = -233.5$  $EIC_{\Lambda} = -239.2$   $EIC_{w} = -241.0$ 

Bayesian information theoretic approach:  $BPIC_{\Lambda} = -237.5$   $BPIC_{w} = -237.3$ 

## Is there a substantial difference?



Generate random artificial data sets assuming ACDM:

Using the Union 2.1 data set we cannot decide wether the  $\land$ CDM or the wCDM model should be preferred.

## Summary of the methods

- With the goodness of fit you rank models according to their ability to fit the data points.
- The likelihood ratio allows you to discard a given model (your null hypothesis) in favour of the alternative model.
- In a Bayesian model comparison you use the evidence ratio to compare the joint probabilities of the models and the data.
- In the classical information theoretic approach you measure how good the best fitting models are at predicting new data.
- In the Bayesian information theoretic approach you measure how good the posterior predictive distributions of the models are at predicting new data.



• Two questions · · ·

Discussion

- Which model, with sufficient data, can be identified as the true model?
- Based on the data, which model lies closest to the true model?
- $\cdots$  two answers?
- Both likelihood ratio test and the Bayesian model selection go for the *truth*: Either you discard the false models via tests, or you determine the most probable model.
- With the information theoretic approach one tries to identify the model which is closest to the true distribution and most effective in predictions.
- BUT: All models are wrong (G. Box).

## AddOn

# Bootstrap for b(f)

Explicating the dependence on the data d

$$b(f) = \mathbb{E}_{F_{T}} \left[ \eta\left(f; \boldsymbol{\theta}^{\star}(\boldsymbol{d}), F_{T}\right) - \eta\left(f; \boldsymbol{\theta}^{\star}(\boldsymbol{d}), F_{T,N,\boldsymbol{d}}\right) \right].$$

- generate bootstrap samples  $\tilde{d} = (\tilde{x}_i, \tilde{y}_i)_{i=1}^N$  from the data by repeatedly drawing from d with putting back (sampling from  $F_{T,N,d}$ ).
- With bootstrap samples  $\widetilde{d}$  from y estimate b(f):

$$\widetilde{b}(f) = \mathbb{E}_{T,N,\boldsymbol{d}} \left[ \eta \left( f; \boldsymbol{\theta}^{\star}(\widetilde{\boldsymbol{d}}), \boldsymbol{F}_{T,N,\boldsymbol{d}} \right) - \eta \left( f; \boldsymbol{\theta}^{\star}(\widetilde{\boldsymbol{d}}), \boldsymbol{F}_{T,N,\widetilde{\boldsymbol{d}}} \right) \right].$$

• Again an asymptotic result, variance reduction possible.

- subjective priors
- objective priors, non-informative priors, reference priors
- priors suggested by preceding results (regress?)

• Two models for generating mocks:

• 
$$\Omega_m = 0.278, w = -1 \text{ (red)}$$

- $\Omega_m = 0.171, w = -0.8$  (blue)
- For each mock calculate

$$\Delta AIC = AIC_{\Lambda} - AIC_{w},$$

$$\Delta BPIC = BPIC_{\Lambda} - BPIC_{w}$$
.

• Empirical distribution

